

# What if

## From Counterfactual Worlds to Semantic Kernels



*Jim Kazanjian, untitled*



*Marvellini, Goldrake Cilindro*

“ We do not know a truth without knowing its **cause**. ”  
*Aristotle*

**Student: Cieri Manuel**

**Mentor: Prof. De Prisco Roberto**

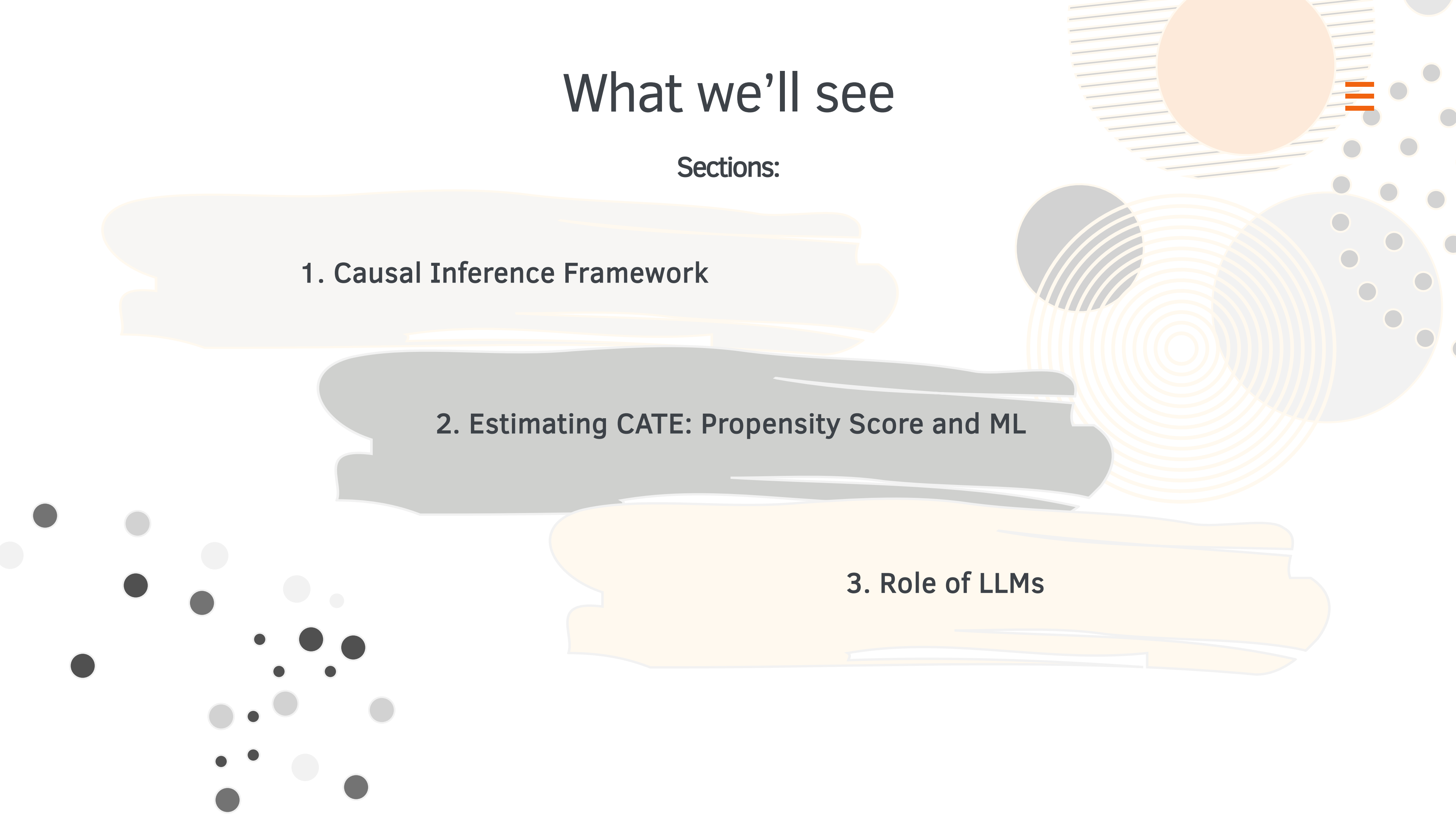
# What we'll see

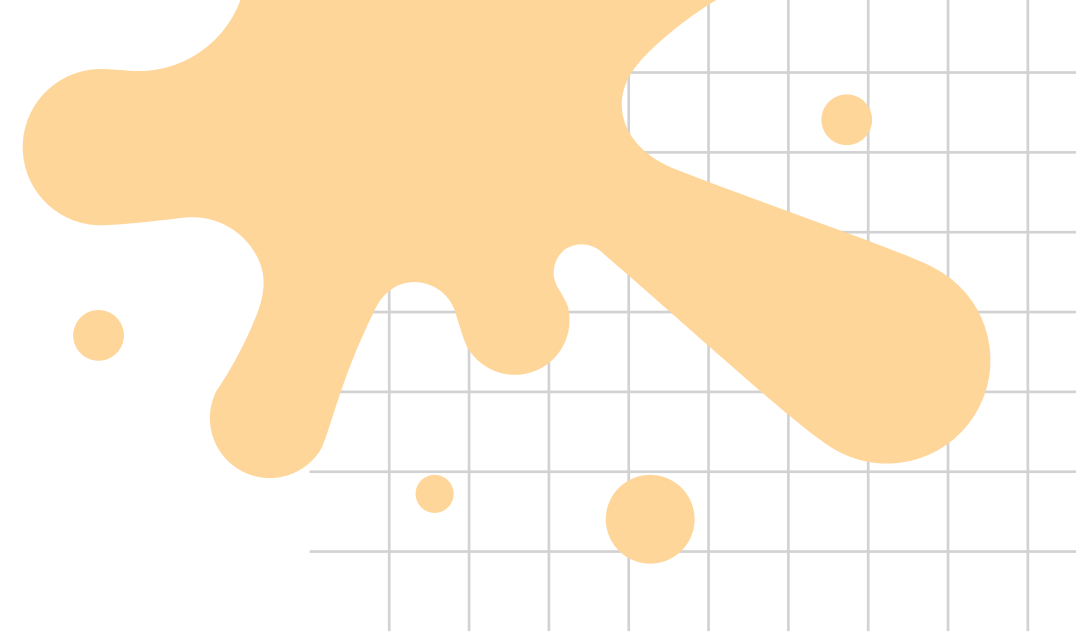
Sections:

1. Causal Inference Framework

2. Estimating CATE: Propensity Score and ML

3. Role of LLMs

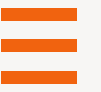




# 1. Causal Inference Framework



# What is Causal Inference?



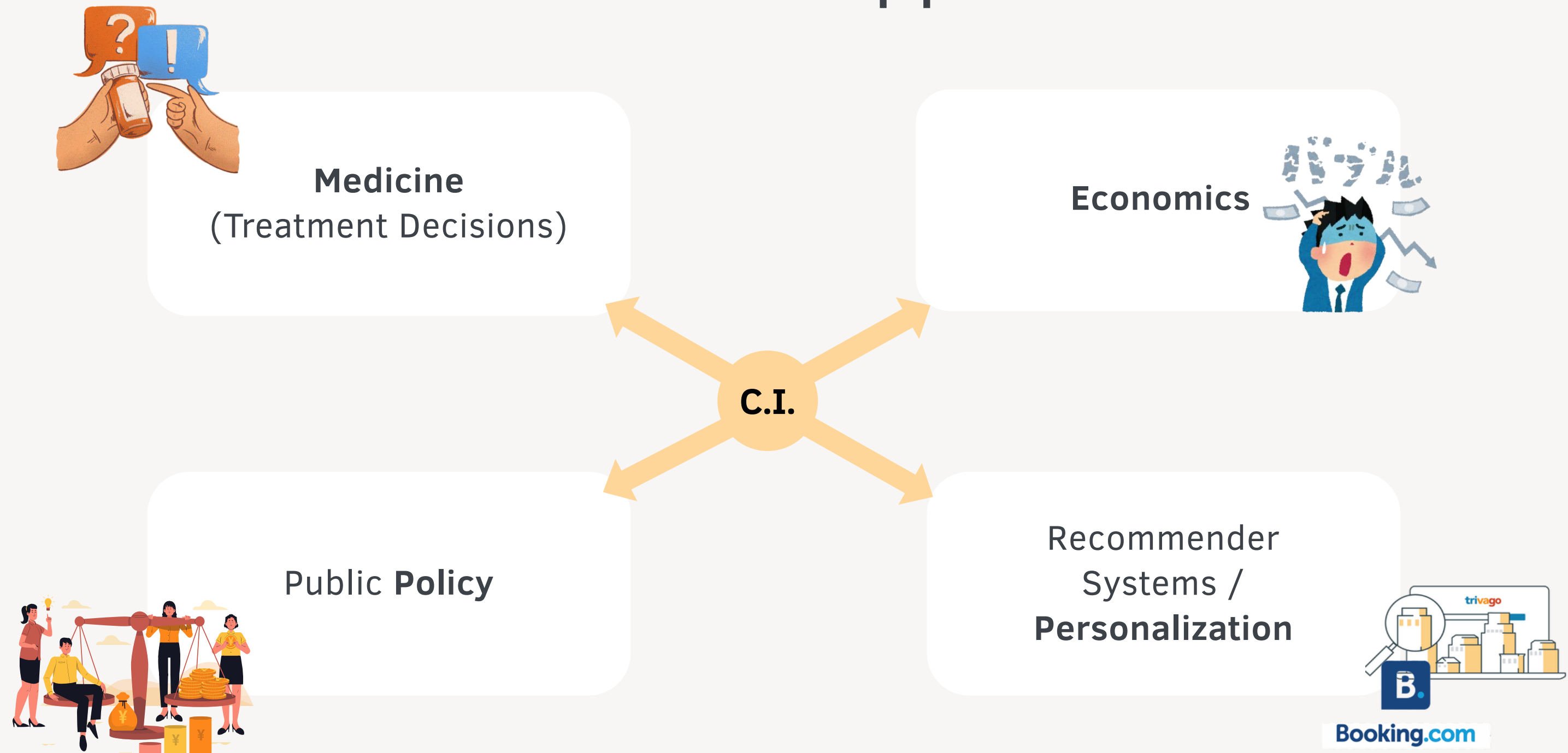
## Causal Inference:

**Methodological Approach** to define **cause-effect relations** among variables

We'll use as statistics foundation and terminology:  
**Rosenbaum and Rubin Framework (1983)**

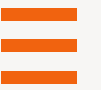
**Causes of nature** have been always **investigated** throughout **history**

# Where is It Applied?



**Causal inference asks: *what would happen if we acted differently?***

# Treatment Effect



**Machine learning** predicts *what is likely*.  
**Causal inference** predicts *what would happen if*.

- Beyond correlation
- Central to **decision-making**

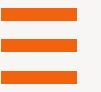
Given an action/intervention that we call “**treatment**”, what is its effect on a defined **outcome**?

$$\text{Effect of “Treatment” } \tau = Y^1 - Y^0$$

$T$  : **Intervention** or Treatment  
 $Y^0$  : Outcome if X in **Control** Group  
 $Y^1$  : Outcome if X in **Treatment** Group

Predicting outcomes under hypothetical actions

# The Missing World



- Each unit has **two potential outcomes**
- We **observe only one**
- The **other is counterfactual**

Observed Outcome

$$Y_i^{obs} = T_i \cdot Y_i^{(1)} + (1 - T_i) \cdot Y_i^{(0)}$$
$$T_i \in \{0, 1\}$$

**Individual Treatment Effect (ITE)**

$$\tau(x) = Y^1 - Y^0$$

# A Simple Example



**Goal:** “Elevating Computer Science in Italy” - **Idea:** Help CS students.  
How? We need to define a specific treatment.

Let’s consider **Bruno Jr:**

**Treatment:**

Partecipating in “Scuola Ortogonale”



$Y^1$

**Brescia Award**  
for Scientific Research

**Control:**

Not Partecipating in “Scuola Ortogonale”



$Y^0$

WebDev lost job to Claude,  
got rejected from art school also

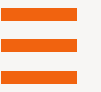
For each student we  
want to know if **policy**  
is **good or not**

**Outcome:**

CS Achievements in X years

**We can only observe one!**

# The Fundamental Problem



- **Potential** outcomes:  $Y^0, Y^1$
- **Observed** outcome:  $Y = Y^T$
- **Fundamental problem:** *we never observe both*



## Solutions?

1. We could observe a **parallel counterfactual universe...**

**Note!**

We'll focus on **Causal Inference in Medicine**



# Why Average Effects Are Not Enough

1. ...or we can **estimate** it through approximate metrics

**Average Treatment Effect**

$$ATE = \mathbb{E} [Y^1 - Y^0]$$

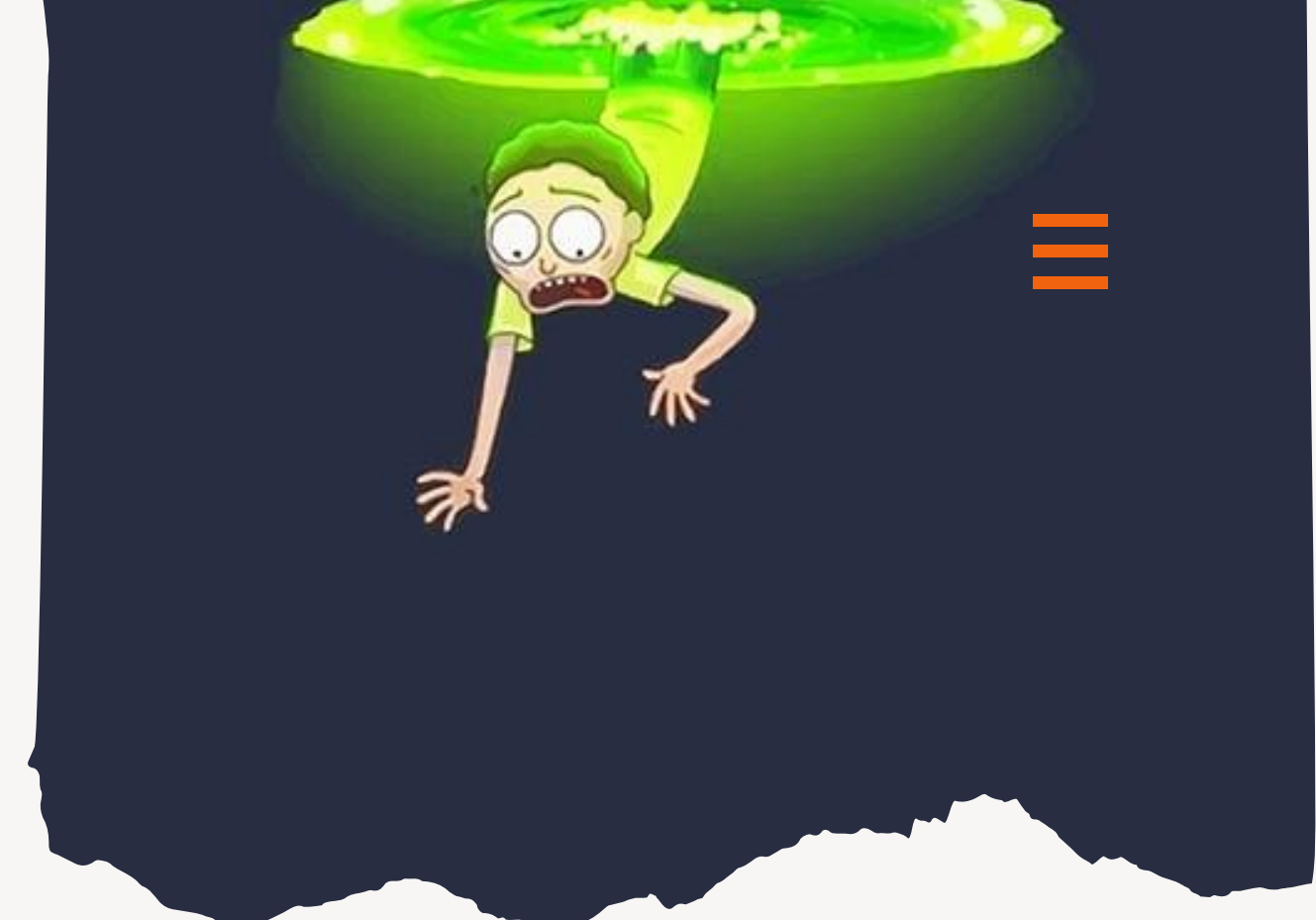
But:

- Decisions are individual
- Treatment effects are heterogeneous
- **Policy requires personalization**

**Conditional Average Treatment Effect**

$$CATE = \mathbb{E} [Y^1 - Y^0 \mid X = x]$$

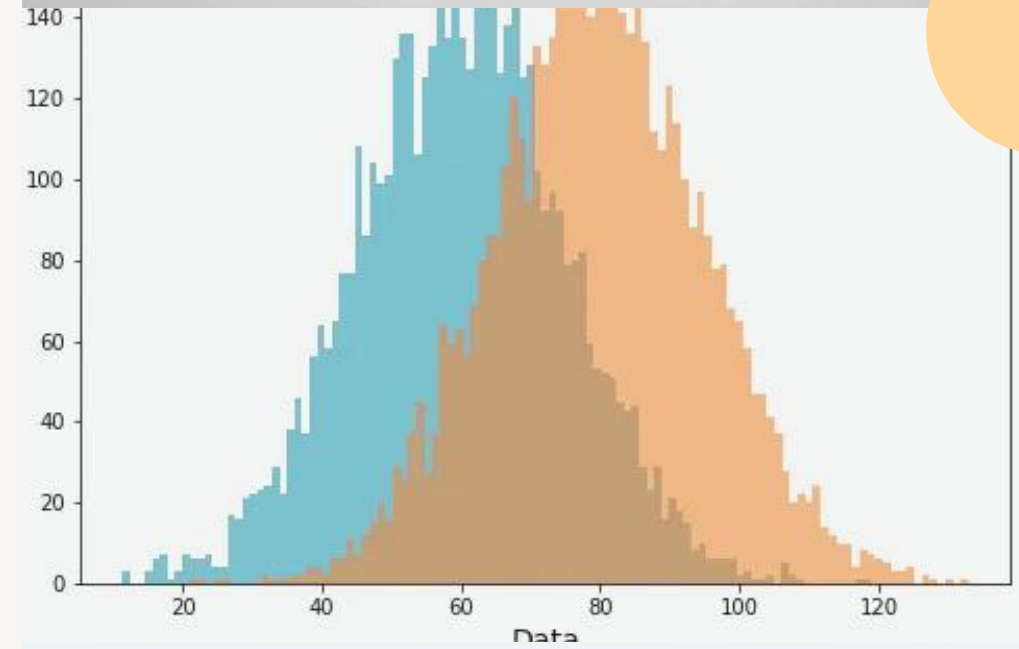
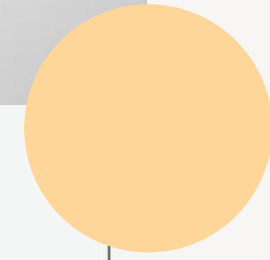
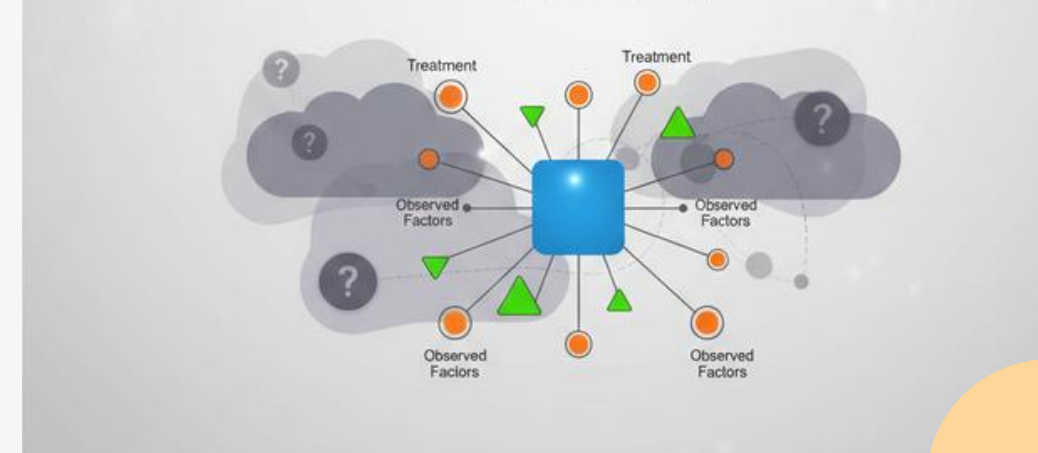
- **Personalization** requires  $\tau(x)$
- Harder: **needs stronger assumptions**



## ● How Find Counterfactual

When Data is good: we can identify a “*counterfactual twin*” in the other group with equal/most similar covariates

# When Is CATE Identifiable?

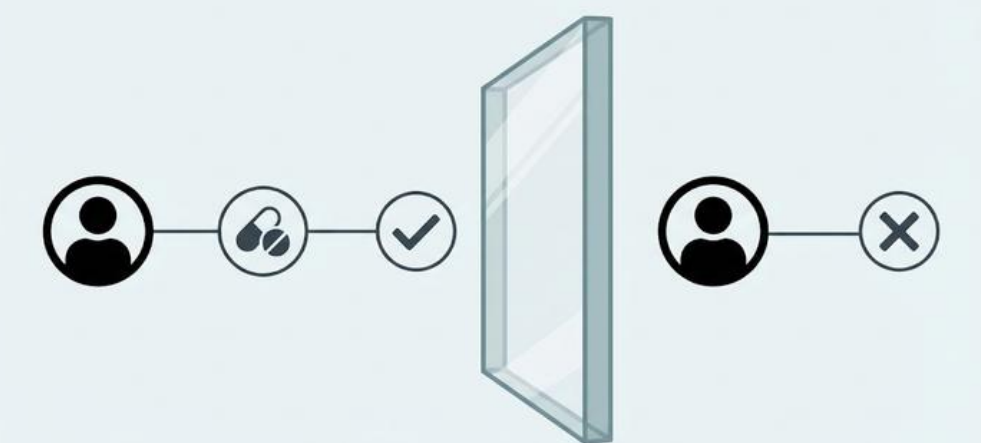


## Key Assumptions

- **Stable Unit Treatment Value Assumption:**
  - **Consistency** → observed = realized potential outcome
  - **No Interference:** T=t on subject x doesn't affect subject y
- **Ignorability** → no hidden confounders
- **Positivity (overlap)** → both treatments possible

$$(Y^0, Y^1) \perp T \mid X$$

$$0 < P(T = 1 \mid X) < 1$$



# Stress Testing CATE in Observational ICU Data



**Gold Standard:**  
Randomized Controlled Trials

**Randomness**  
guarantees  
similar distributions

**RCTs**

Verified **Positivity** and  
**Exchangeability**

**Often Available**

Real-world  
**observational** dataset

**Observationals**

Most comparisons  
failed due to  
**imbalance**

**Selection Bias:**  
Treatment and Outcome  
both condition Inclusion  
in test

**Confounding Bias:**  
external variable  
common cause of  
Treatment and Outcome

$$(T \rightarrow I \leftarrow Y)$$



$$(T \leftarrow X \rightarrow Y)$$

We used: **MIMIC-IV** Dataset

In practice, estimates often collapse.



## Our Work



**1. Identify subsets**  
with different bias scale



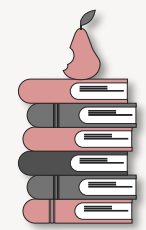
**2. CATE estimation**  
with known tools



**3. Bias Tool**  
Add a quantifiable bias  
both absolute and  
“relative”



**4. Use LLMs for direct  
CATE inference**



## Large Observational Dataset

+200k Hospitalized in Emergency Dpt  
+65k Unique ICU Stays

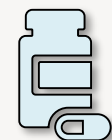
About 30 different tables with:



• 2M+ Chart Events 

• 2M+ Lab Events

• Patient Diagnoses 



• Procedures and Pharmacy

• Outcome and Output Events (i.e. in-hosp mortality)



Note: our results are presented  
when you see this icon



# Structural Confounding



## Vasopressors in ICU

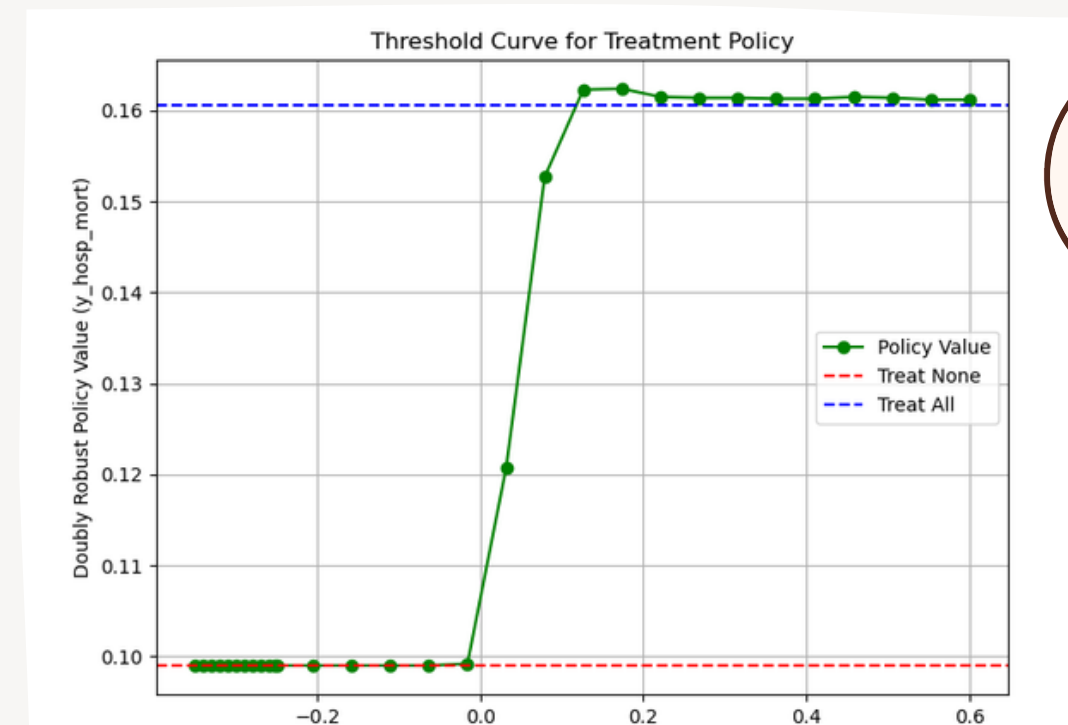
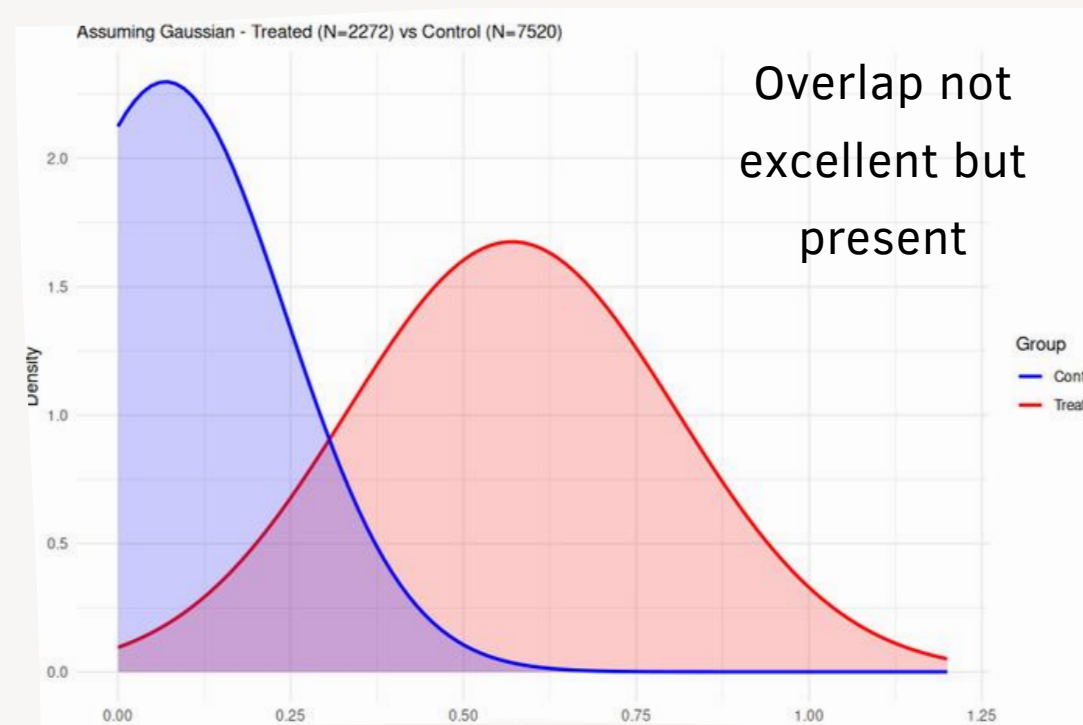
- **Y** = In-hospital Mortality
- **IPTW**  $\approx +0.064$
- **AIPW**  $\approx +0.058$
- **ATO**  $\approx +0.047$

### ● Confounding by Indication

- Familiarizing with MIMIC-IV dataset
- **Treatment appears harmful** even after DR estimation
- **Severity** drives both **treatment** and **outcome**

CATE worst outcome than “treat none” policy:  
**Vasopressors worsen outcome?!**

When X does not capture severity, ignorability fails.



Maybe I shouldn't use Epinephrine...





## 2. Estimating CATE: Propensity Score and ML

# Estimating the Missing World

All these methods rely implicitly on **balancing distributions**

Inverse Probability  
Weighting

$$\hat{\tau}(x) = \hat{\mu}_1(x) - \hat{\mu}_0(x)$$

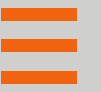
ML models

Meta-learners

Doubly Robust  
estimators

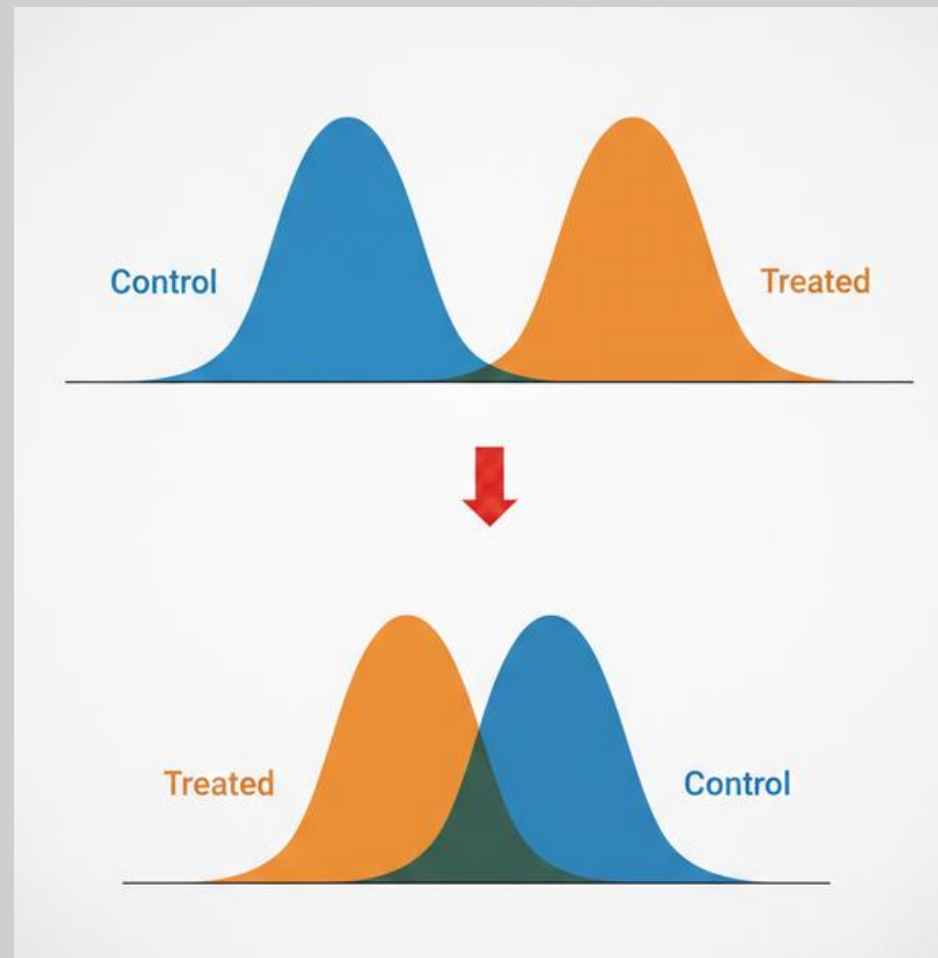
We'll focus on the tools and bounds as demonstrated in  
**Shalit et al. (2017)**

# The Real Difficulty: Distribution Shift

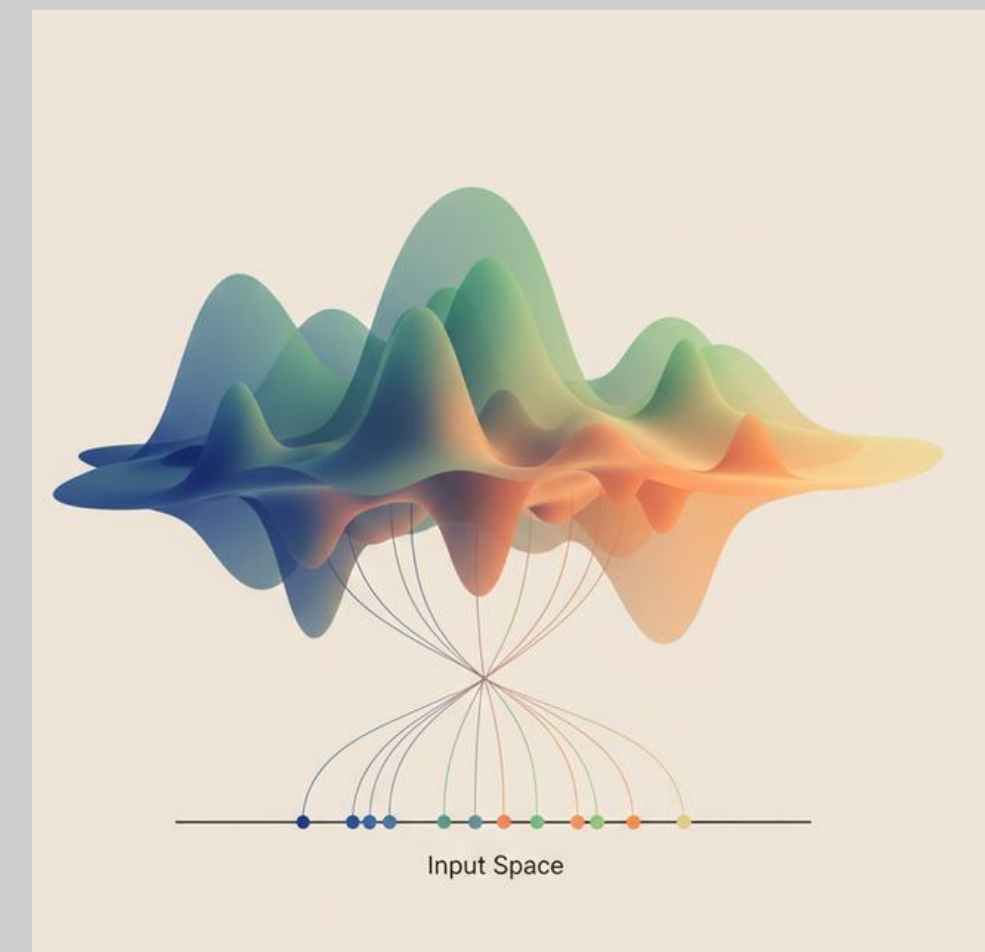
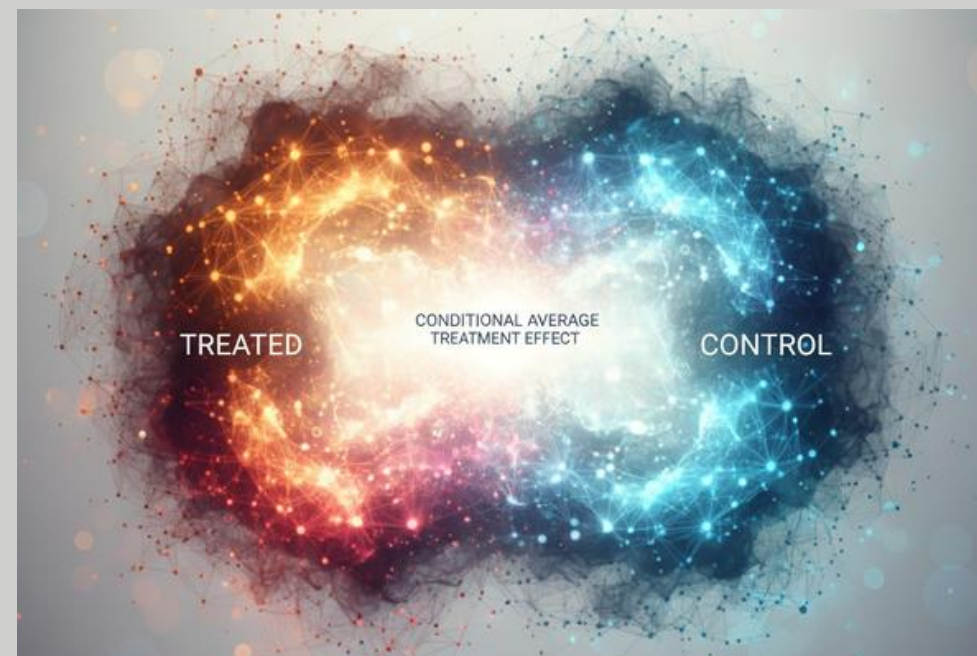


Treated and control  
differ in covariates

- Counterfactual = extrapolation
- Poor overlap → unstable CATE



**CATE estimation is fundamentally a domain adaptation problem.**



# Propensity Score as Compression



$$e(X) = P(T = 1 | X)$$

## Balancing Score

Conditional to  $b(x)$ ,  
covariate distribution  $X$  is  
**independent** from treatment  
assignment  $T$ :

$$X \perp T | b(X)$$

## Propensity Score

- Rosenbaum & Rubin (1983)
- **Probability of Treatment given covariates  $X$**
- Weighting and **Stratification** over  $e(X)$  make observational data **RCT-like**

## Compressing Imbalance

- Balancing property
- **Reduces dimensionality**
- Does not solve complex geometry
- **Sufficient** for confounding adjustment

Propensity score **reduces imbalance to one dimension**,  
but geometry may still be high-dimensional.



# Designing for Overlap



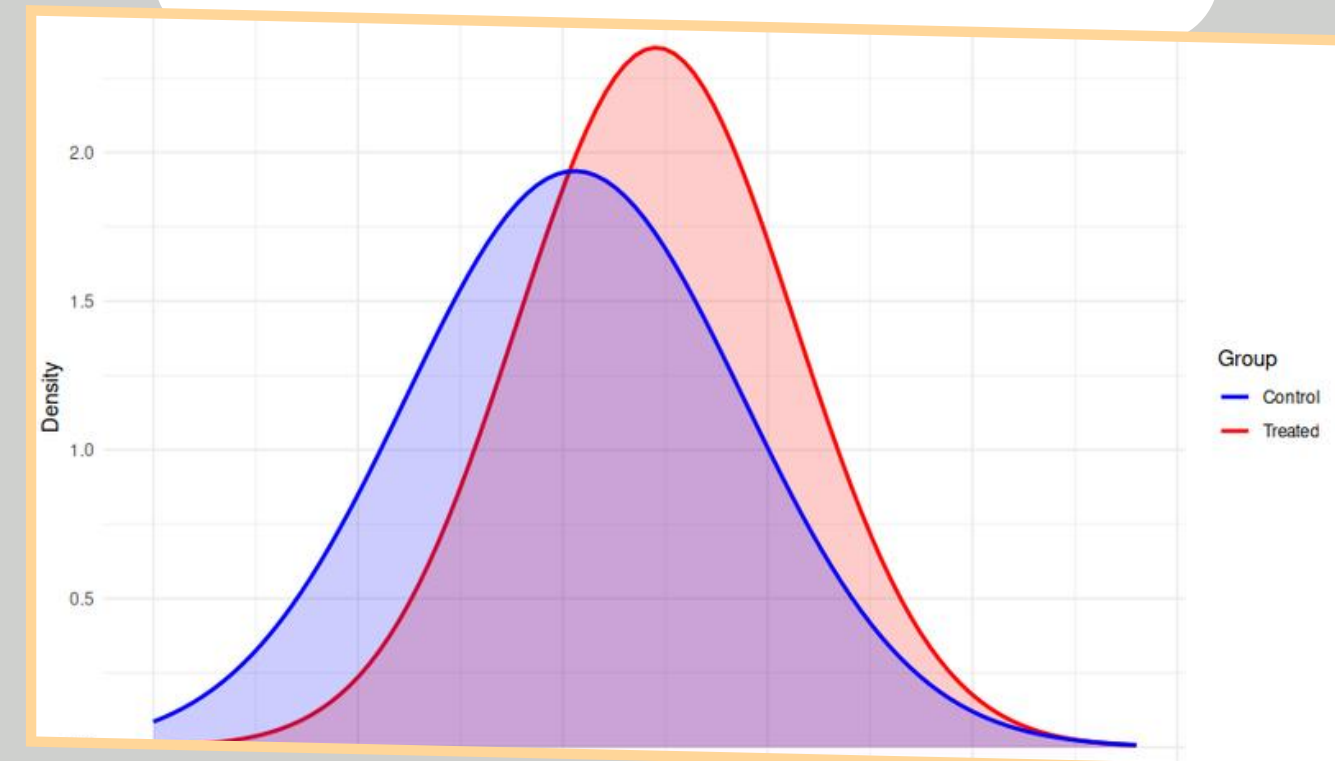
## A (Slightly) **Better Design**: Early Diuretics in Sepsis

- N = 6,216 ICU patients
- Landmark design ( $t_0$  = sepsis + 6h)
- Excluded active shock on admission
- Treatment = **early vs delayed diuretics**

CATE is **estimable** but still **inconsistent!!**

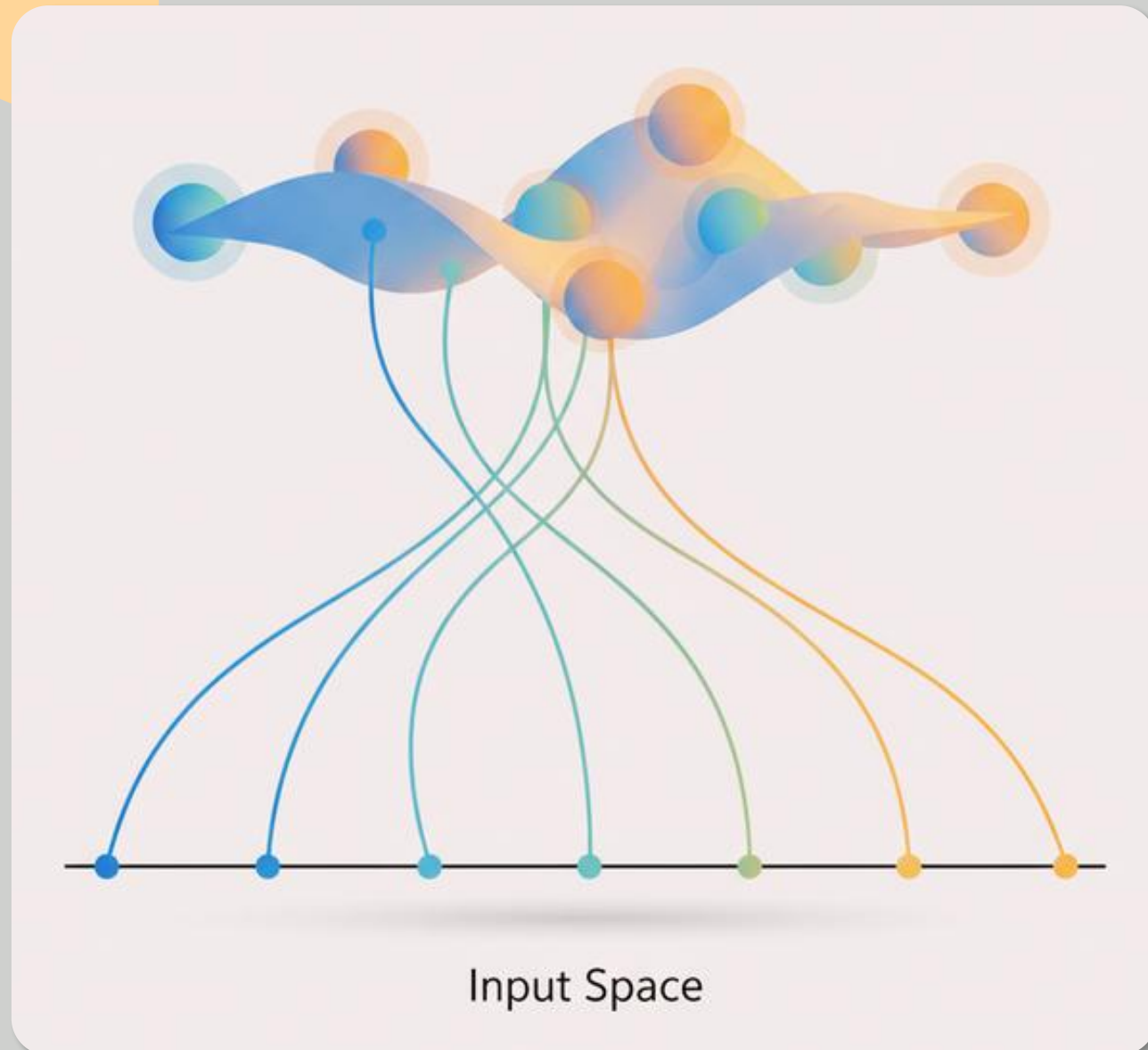
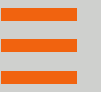
### Overlap Enables Identification

- No dominant strata
- **Balanced covariates**
- **Bias still present!**



Careful temporal design reduces confounding,  
but sometimes not enough.

# Beyond Means: Comparing Distributions



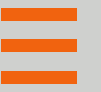
- Means are not enough
- **PS** for balance but **ignores covariates** for **outcome** estimates
- Need **distribution-level comparison**
- Introduce **similarity function**

$$k(x, x') := \langle K_x, K_u \rangle_{\mathcal{H}}$$

A Kernel defines here a notion of **local similarity**

If we define similarity, we can compare groups structurally.

# Kernel-Based Balancing in Practice



Overlap is not absolute: it depends on how we encode the data.

- Kernels in Representation Learning

$$k(x, x') = \exp\left(\frac{-\|x - x'\|^2}{2\sigma^2}\right)$$

- **Kernel defines similarity** in feature space
- Common choices: Radial Basis Function (RBF), linear, polynomial,...
- **Geometry is fixed** by chosen kernel

Classical kernels impose a predefined geometry.

# Why Balancing Improves CATE



$$\varepsilon_{PEHE} \leq 2(\varepsilon_F^{(1)} + \varepsilon_F^{(0)}) + 2B_\Phi \cdot IPM(p_\Phi^{(1)}, p_\Phi^{(0)})$$

## Theoretical Justification (Shalit et al., 2017)

Precision in Estimation of  
Heterogeneous Effect

$$\varepsilon_{PEHE} = \mathbb{E}[(\hat{\tau}(x) - \tau(x))^2]$$

Basically, **Mean Squared Error**  
(MSE) between estimation and  
real outcome

Representation learning is not  
heuristic but it has theory behind it.

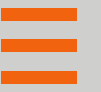
Integral Probability Metrics  
(IPM)

Error decomposes into:

- **Factual prediction error**
- **Distribution imbalance**
- Reducing IPM reduces  
counterfactual error
- **Geometry directly affects  
identifiability**

This is essentially a domain adaptation upper bound applied to causal inference.

# MMD: Measuring Imbalance

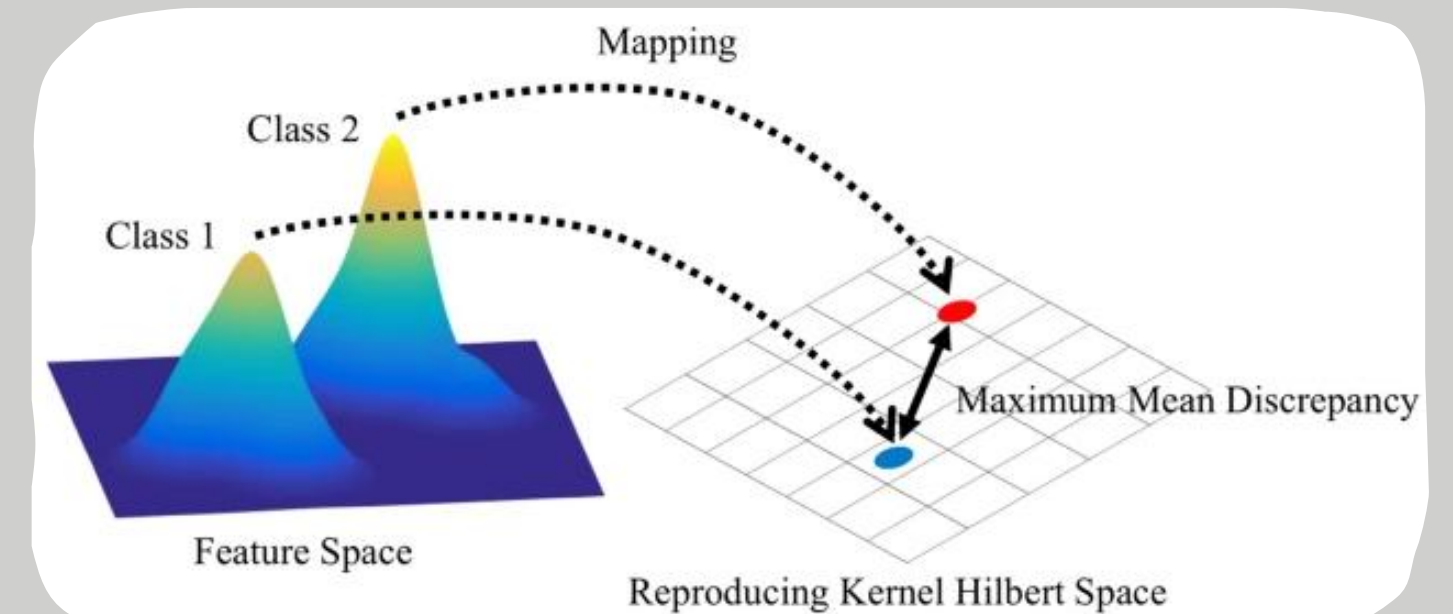


## ● Maximum Mean Discrepancy

$$MMD^2 = \mathbb{E}[k(X, X')] + \mathbb{E}[k(Y, Y')] - 2\mathbb{E}[k(X, Y)]$$

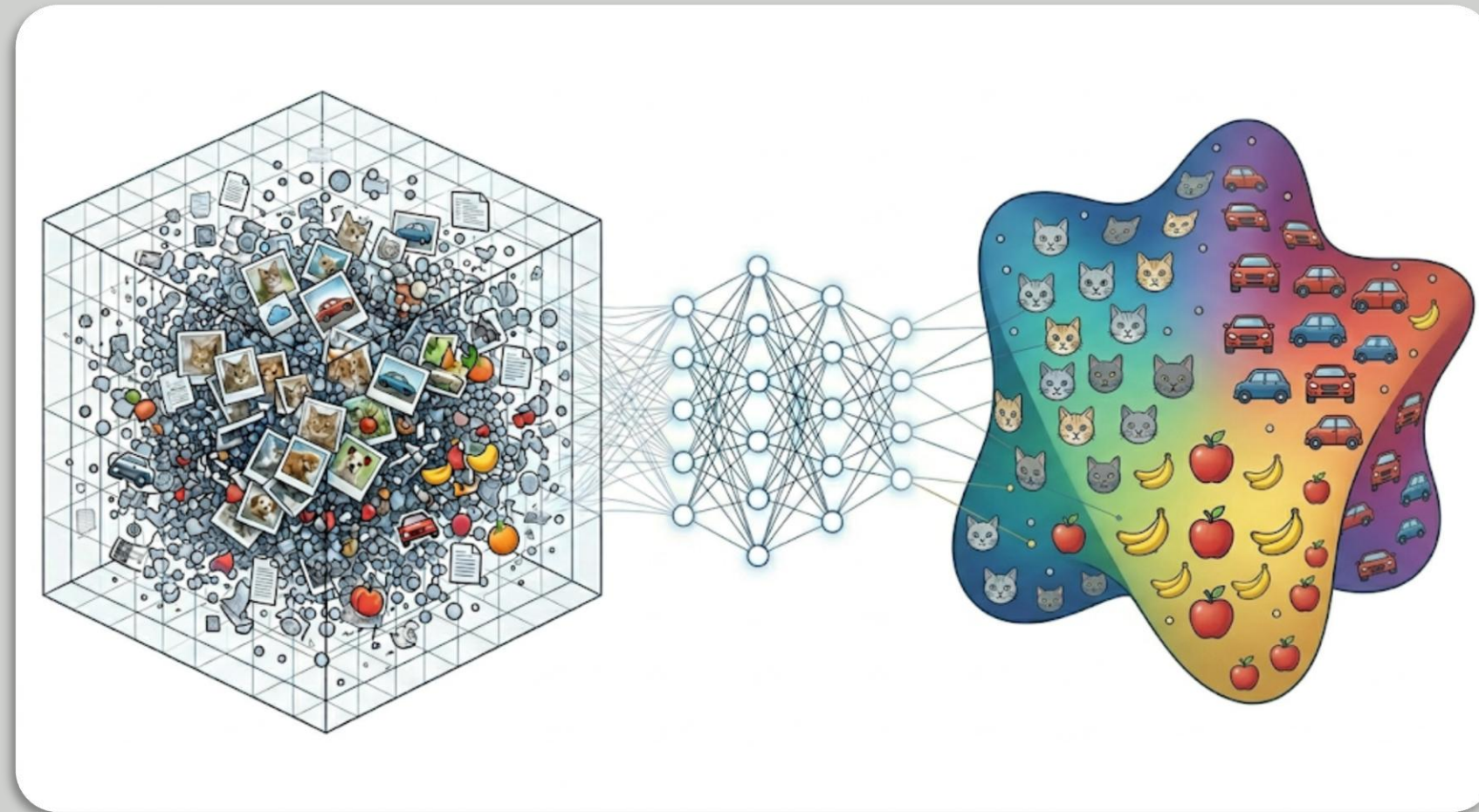
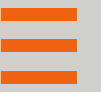
Within-group similarities                      Between-group similarity

Measures distribution gap



We now have a geometric distance metric for distributions too

# Learning a Better Geometry



- Learn representation  $\Phi(X)$
- Reduce imbalance in latent space
- Improve counterfactual stability

$\Phi(X) \rightarrow$  induced geometry

$$\mathcal{L} = \text{Outcome Loss} + \alpha \cdot IPM$$
$$p(\Phi(1)) \approx p(\Phi(0))$$

Better representations may improve balance and reduce extrapolation error.

# Representation Learning for CATE



$\Phi(X) \rightarrow$  induced geometry

- 1 • **Shared representation**  $\Phi(X)$ 
  - **Separate outcome heads**
  - Explicit **balancing regularization**

- 2 • **TARNet**: shared representation + two heads
  - **CFRNet**: TARNet + IPM penalty
  - **DragonNet**: (Shi et al.)
    - adds propensity head + targeted regularization

- 3 **Representation learning turns balancing into optimization.**

$$\mathcal{L} = \text{Outcome Loss} + \alpha \cdot \text{IPM} + \mathcal{L}_{\text{targeted}}$$

$p(\Phi(1)) \approx p(\Phi(0))$

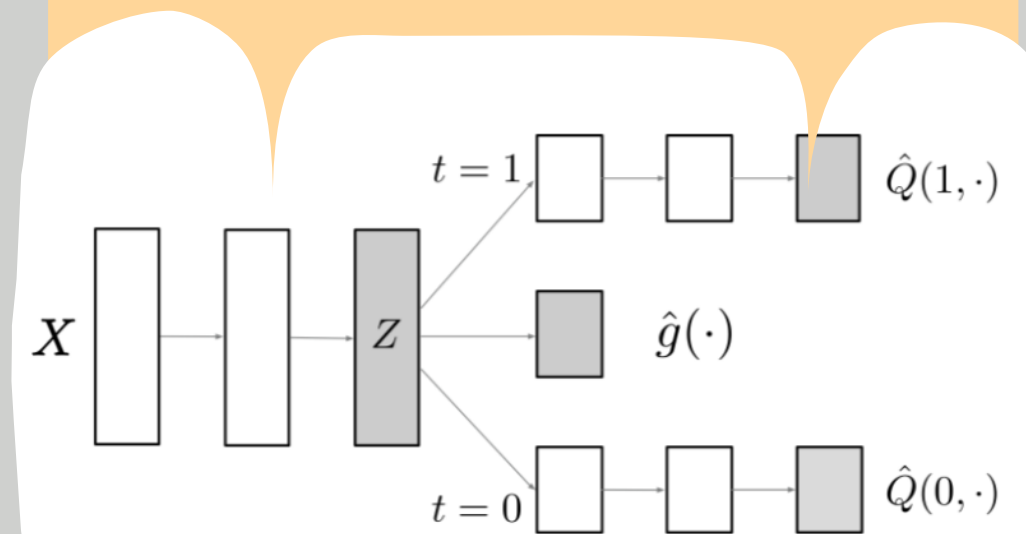
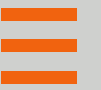


Figure 1: Dragonnet architecture.



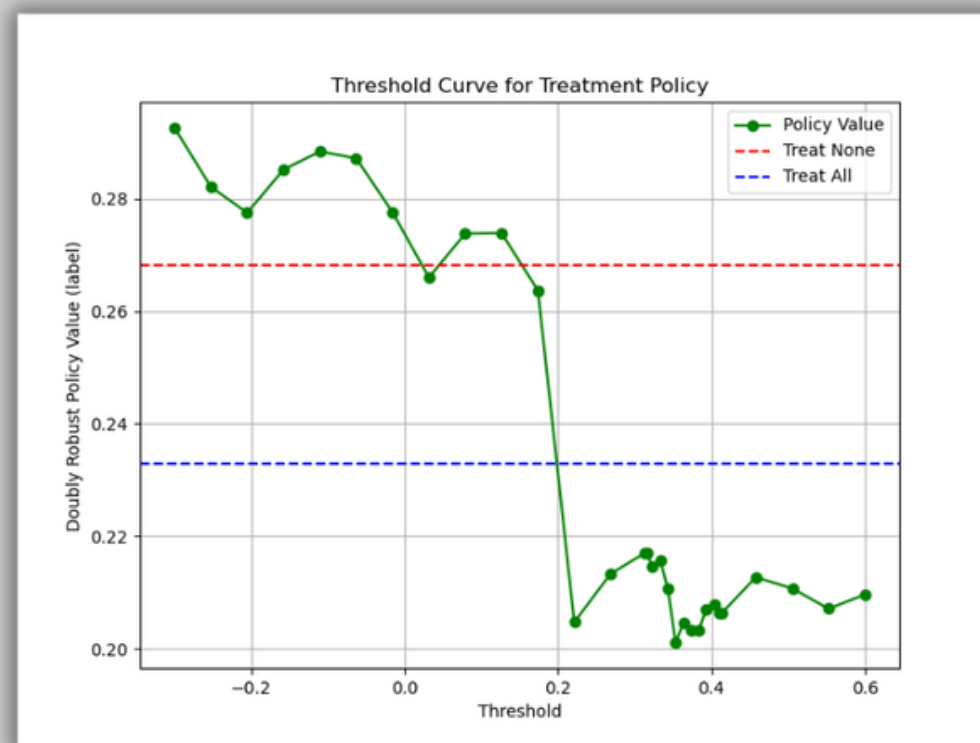
# From Average Effect to Decision Rule

aka Policy



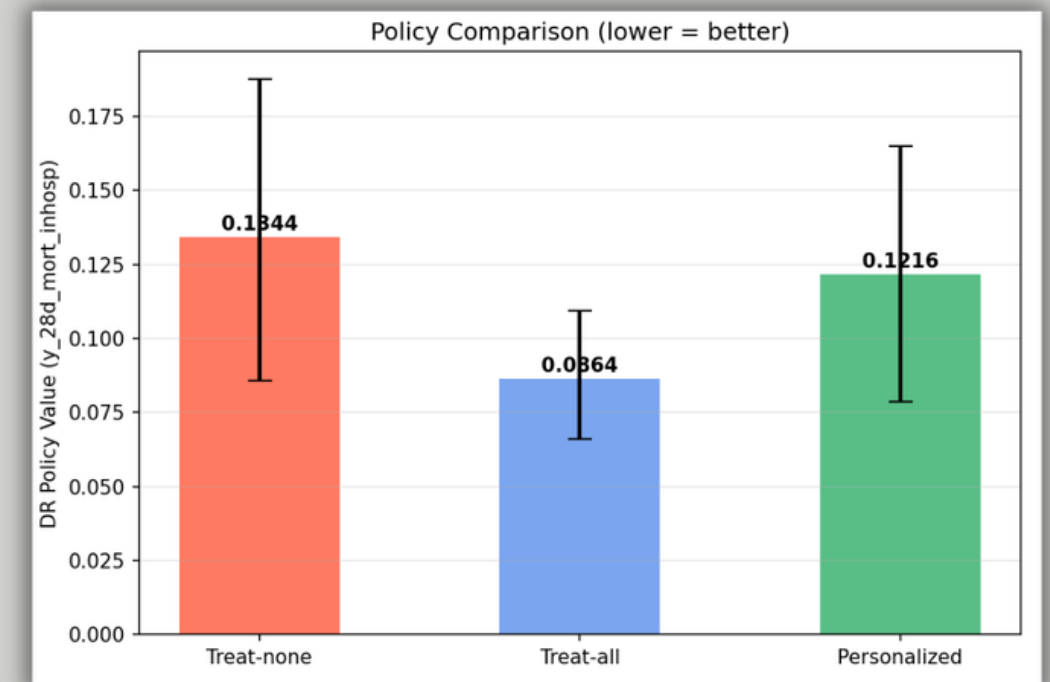
## Policy

- After estimates we can define a **treatment policy**: e.g. on threshold
- Ideally if CATE is perfect: treat only if  $t(x) < 0$



## From CATE to Policy

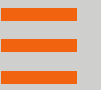
- **Treat-all globally optimal**
- Personalized policy  $>$  treat-none
- Strong heterogeneity present
- Still lot of **noise and bias**



But CATE stills reveals structure beyond ATE.



# Treatment Effect Heterogeneity

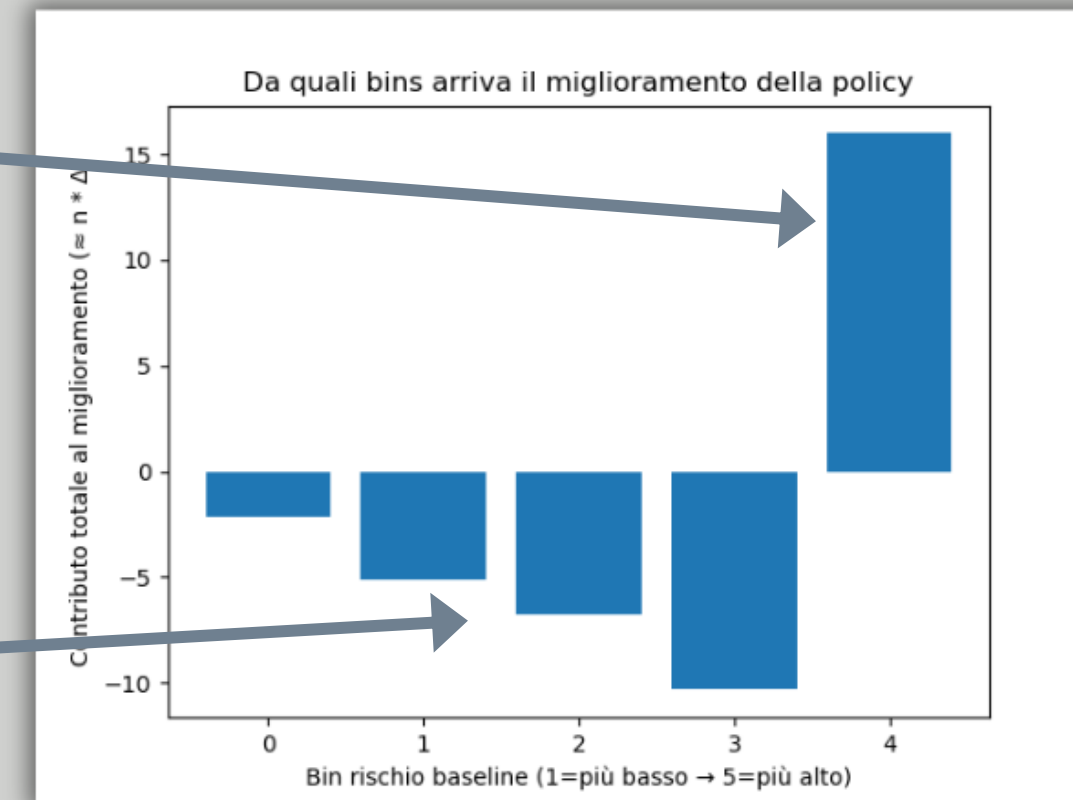


Back to Early vs Delayed Diuretics in Sepsis

High-risk patients  
benefit substantially

Clinical coherence  
with severity

Low-risk  
unhelpful or slightly  
harmful (?)\*



*Unable to define a correct policy.*

- **Still bias:**  $\tau(x) > 0$  for treatment group even if mortality decrease
- **Inconsistencies** in policy and CATE estimates

\* Only for a **tiny subgroup**: for most is still helpful.  
The rest is noise.



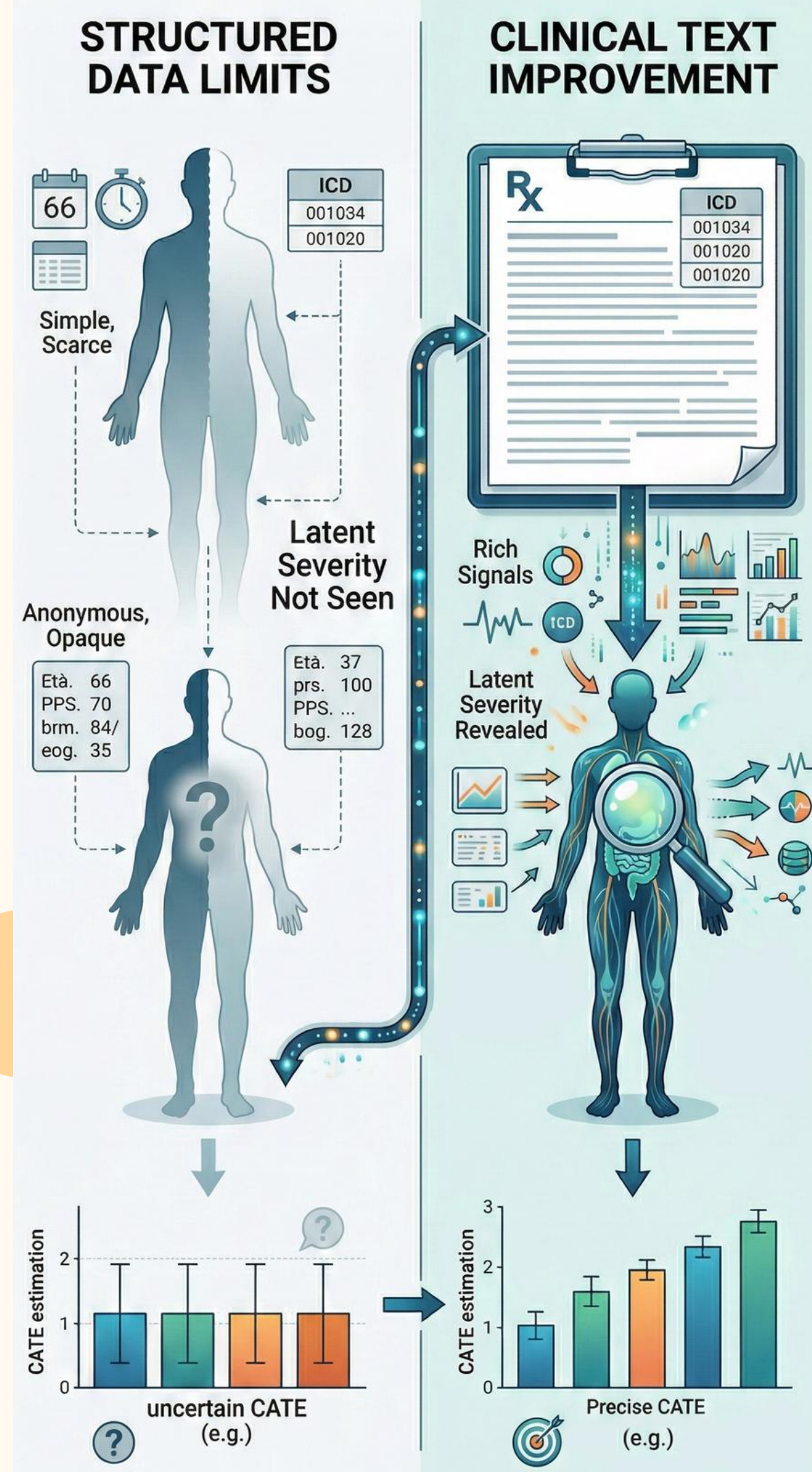
### 3. Role of LLMs

# When Covariates are Incomplete

## ● Limits of Tabular Covariates

- **Clinical text** contains **rich** signals
- Severity is partially **latent**
- Structured variables are **coarse summaries**
- **Ignorability** depends on **feature richness**

If relevant **confounders** are **missing** from **data**,  
no estimator can fix it.



# LLM Embeddings as Semantic Kernels



Foundation Models are being used as Representation Engines

- Pretrained **semantic embeddings**
- Implicit **feature construction**
- Potentially **richer confounder encoding**

$$\Phi_{LLM}(x) \in \mathbb{R}^d$$
$$k_{LLM}(x, y) = \langle \Phi(x), \Phi(y) \rangle$$

- Use of **unstructured data** like medical reports

## Semantic Similarity:

e.g. Idiopathic - Primary

- **Classical Learner:**  
2 separate categories
- **LLMs:** semantically the same

LLMs may define a new geometry for causal inference.

# Open Research Questions



## Human-in-the-loop

**Expert:** Validates or corrects priors  
(Domain Expertise).

## Causal for LLMs

Improve **Reasoning Capacity** of LLMs helping understand **cause-effects** relationships

- Can **semantic embeddings** improve overlap?
- Can they **reduce hidden confounding**?
- How to **integrate** with **DR estimators**?
- How to **validate causal consistency**?

## Active Causal Learning

**LLMs** now **passive**: they only analyze data.

Possible Future:

1. Agent identifies ambiguities
2. Self-presents an intervention
3. Analyzes results and updates its prior

## Neuro-Symbolic Systems

**LLM** (Semantics): Priors

**Symbolic Solver** (Math): Estimating Effect

**Deep Learning** (Geometry): MMD and Representation Learning

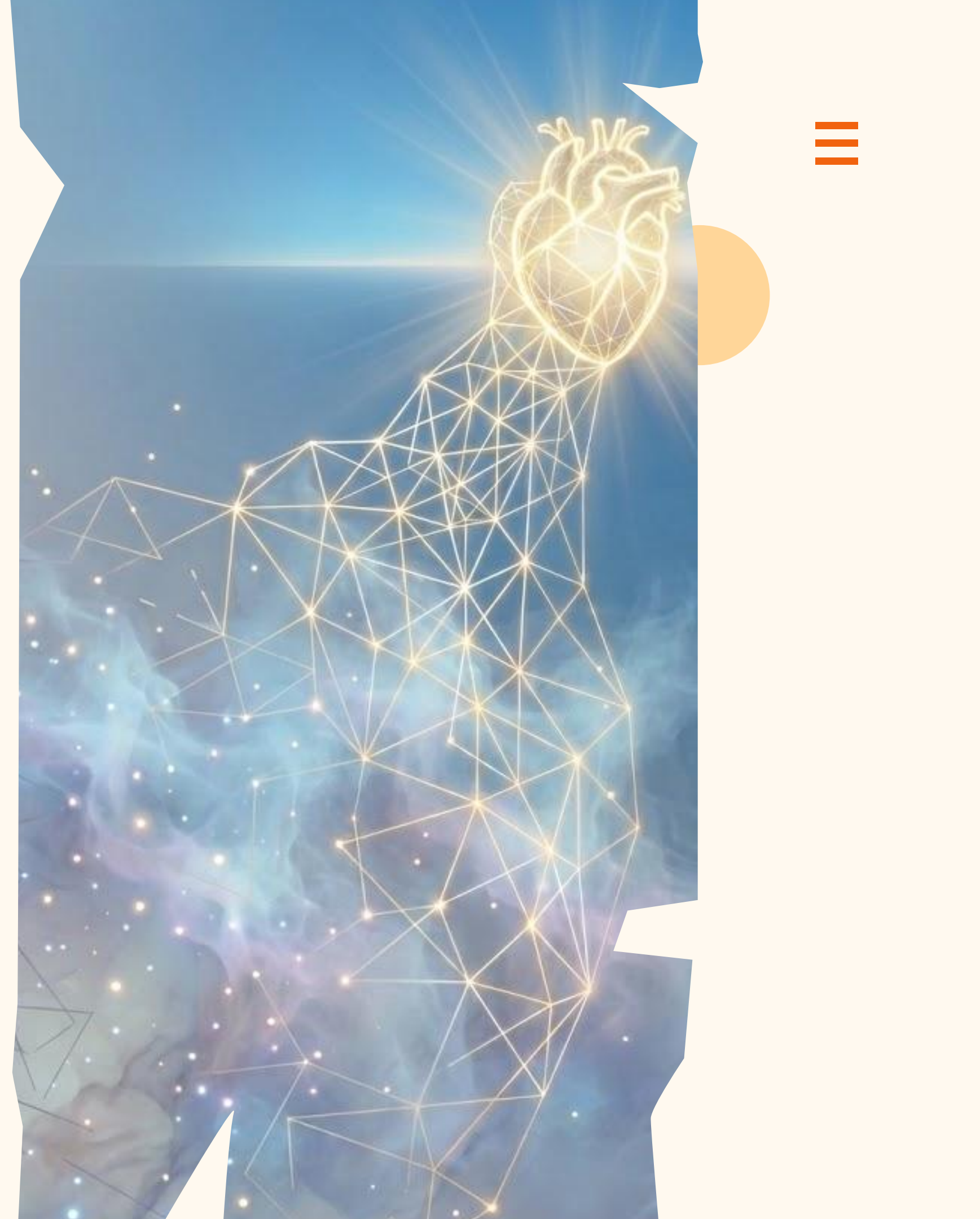
# Takeaways

## Causale Inference and CATE

- **CATE estimation** is fundamentally geometric.
- **Overlap is essential** for identifiability.
- **Design matters** more than algorithm.
- **Representation learning** may be the key.
- **LLMs** are being integrated in the loop

We cannot access the counterfactual world,  
but **we can engineer better geometries.**

**Causa latet: vis est notissima.** *Ovid, Metamorphoses, IV. 287.*



# References

## Theory and ML

- **Rosenbaum, P. R., & Rubin, D. B. (1983).** The central role of the propensity score in observational studies for causal effects. *Biometrika*.
- **Gretton, A., et al. (2012).** A kernel two-sample test. *JMLR*. (MMD Paper).
- **Shalit, U., Johansson, F. D., & Sontag, D. (2017).** Estimating individual treatment effect: generalization bounds and representation learning. *ICML*.
- **Shi, C., Blei, D. M., & Veitch, V. (2019).** Adapting neural networks for the estimation of treatment effects. *NeurIPS*. (Dragonnet).
- **Hernan, M. A., & Robins, J. M. (2025).** *Causal inference: What if*. CRC Press.

## LLMs and Causality

- **Kiciman, E., et al. (2023).** Causal Reasoning and Large Language Models: Opening a New Frontier for Causality. *ArXiv*. (Microsoft Research).
- **Zhang, C., et al. (2023).** Understanding the causal reasoning capabilities of large language models. *ArXiv*.

ELICSIR FOUNDATION



# Thanks!

**Student: Cieri Manuel**

**Mentor: Prof. De Prisco Roberto**



# Bound Expanded (Q&A)



$$\epsilon_{PEHE} \leq 2(\epsilon_F^{(1)} + \epsilon_F^{(0)}) + 2B_\Phi \cdot IPM(p_\Phi^{(1)}, p_\Phi^{(0)}) - 2\sigma_Y^2$$

- Factual risk  $\epsilon_F^{(t)}$
- Lipschitz constant  $B_\Phi$
- IPM term controls domain shift
- Irreducible error  $-2\sigma_Y^2$

- PEHE is limited by **sum of errors on each component** (Y(1), Y(0))
- We'll use triangular inequality

$$\epsilon_{PEHE} \leq 2(\epsilon_{Y(1)} + \epsilon_{Y(0)})$$

$\epsilon_{Y(1)}$

Expected error on prediction of Y(1) on entire population

- Total **error for Y(1)** is composed by **2 parts**, weighted on **treatment probability u** (for Y(0) is similar):

$$\epsilon_{Y(1)} = u \cdot \underbrace{\mathbb{E}_{x \sim P(X|T=1)}[\text{Loss}]}_{\text{Factual (observed)}} + (1 - u) \cdot \underbrace{\mathbb{E}_{x \sim P(X|T=0)}[\text{Loss}]}_{\text{Counterfactual (unknown)}}$$

- We know the observed error, but we need to **estimate** the **counterfactual**, via IPM:

$$\mathbb{E}_Q[\text{Loss}] \leq \mathbb{E}_P[\text{Loss}] + IPM(P, Q)$$

$$PM_{\mathcal{F}}(P, Q) = \sup_{f \in \mathcal{F}} |\mathbb{E}_{x \sim P}[f(x)] - \mathbb{E}_{y \sim Q}[f(y)]|$$

This inequality comes from the IPM math definition above

- **Replacing** all values:

$$\epsilon_{PEHE} \leq 2 \cdot \left( \underbrace{\epsilon_{\text{Factual}}}_{\text{Observed Loss}} + \underbrace{B_\Phi \cdot IPM_{\mathcal{F}}(\Phi)}_{\text{Distribution Distance}} + C \right)$$

Estimated loss is less than or equal to observed loss plus IPM distance



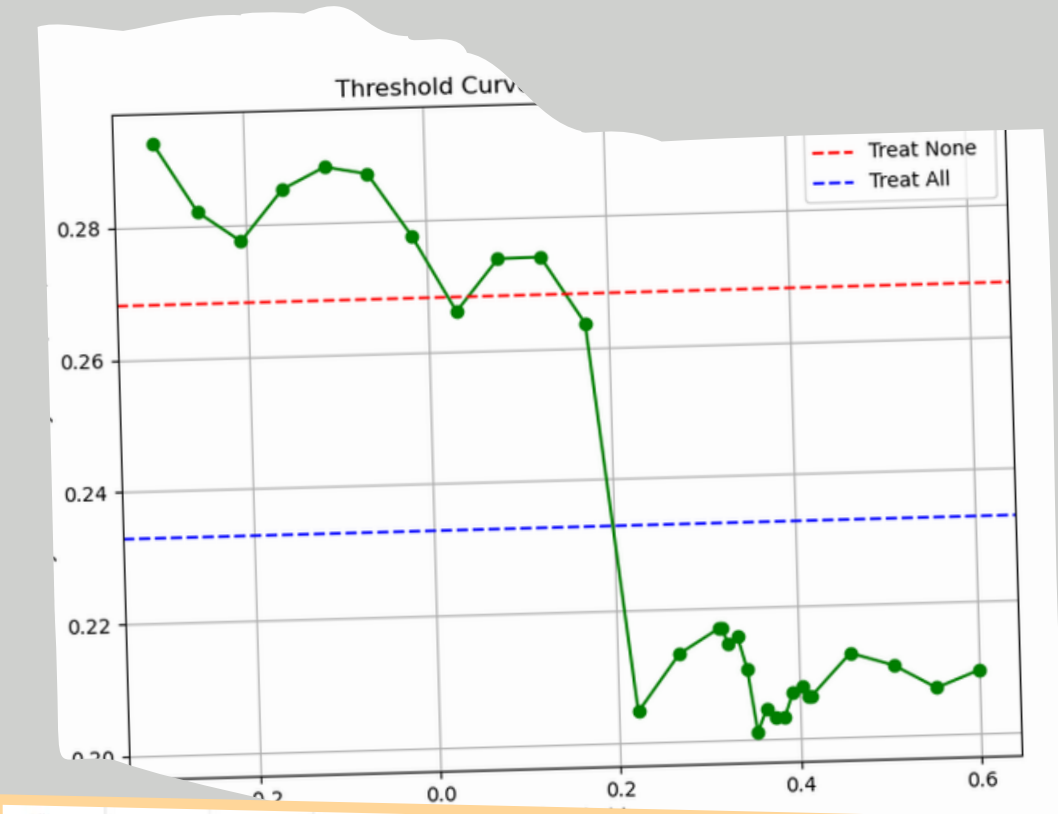
# When we use an RCT instead (Q&A)



CATE is finally  $< 0$  → Better Outcome

## RCT: AIDS Treatment

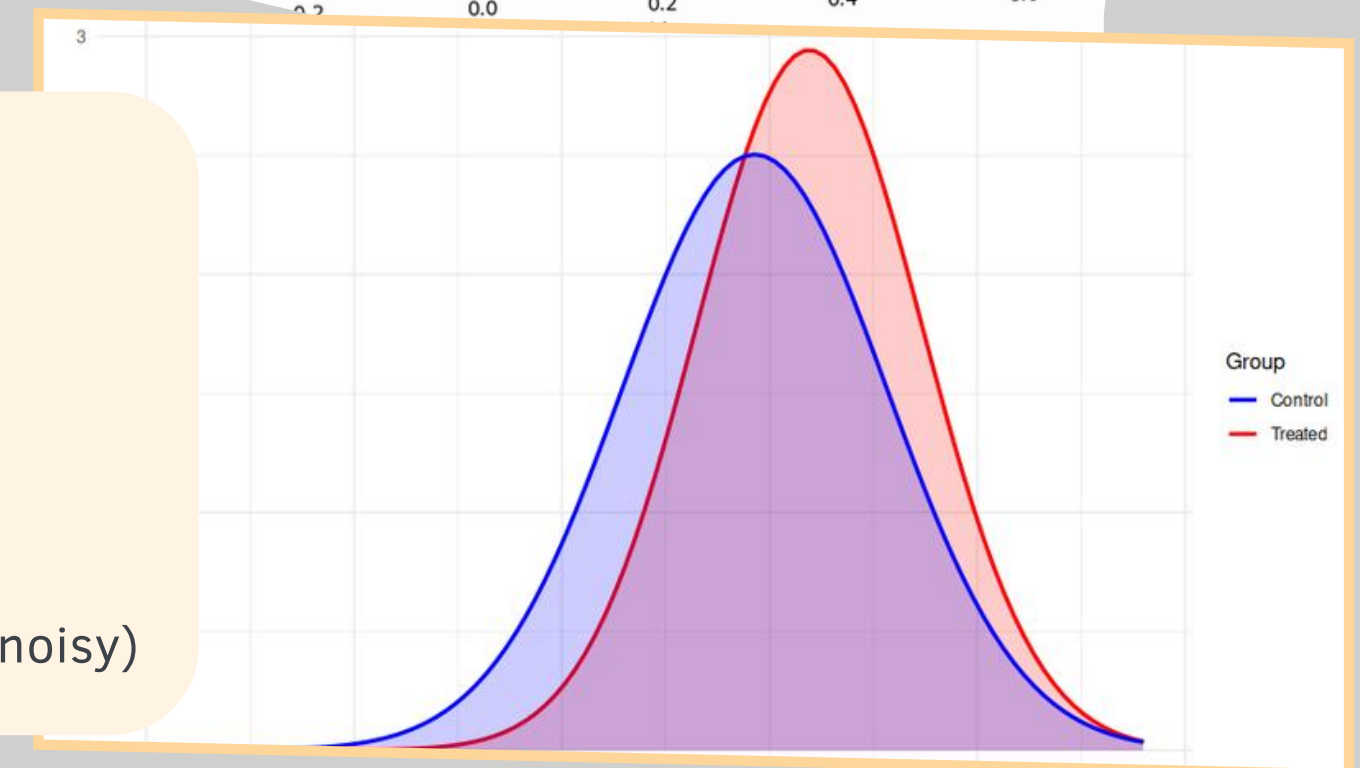
- N = 2139 patients
- **Zidovudine vs Alternative Therapies**
- Outcome: 1:failure, 0:censoring



## Improved data quality

- No dominant strata
- **Balanced covariates**
- **No Bias**

- Naive ATE: -0.0859
- IPW ATE: -0.0696 (propensity weighted)
- DR ATE : -0.0353
- Bias corrected by DR: -0.0507
- **Mean CATE** (tau\_hat): -0.1123 (SD=0.6448)
- **Frac predicted benefit**: 0.545 (tau < 0)
- Heterogeneity SNR: 18.28 (SD/|ATE|, >> 1 = noisy)



RCT is gold standard, bias is strongly reduced

# Representation Models in Detail (Q&A)



## TARNet

- Shared Latent Space
- 2 Separate Heads:
  - Treat Outcome
  - Control Outcome

$$\mathcal{L}_{\text{TARNet}} = \sum_i (Y_i - \hat{y}_{T_i}(X_i))^2$$

No Explicit Causal Term:  
Shares weights but it doesn't  
balance populations

## CFRNet

- Same structure as TARNet
- Adds a **balancing loss** via IPM

$$L = \mathcal{L}_{\text{TARNet}} + \underbrace{\lambda \cdot \text{IPM}(P(\Phi(X) | T = 1), P(\Phi(X) | T = 0))}_{\text{CFRNet: Adds IPM}}$$

- **Global Balance** and outcome independent
- **No use of Propensity Score**

## Dragonnet

- Adds a 3rd Head to CFRNet:  
**Propensity Score Head**
- **Composed Loss**

$$\mathcal{L} = \mathcal{L}_Y + \alpha \mathcal{L}_T + \beta \mathcal{L}_{\text{targeted}}$$

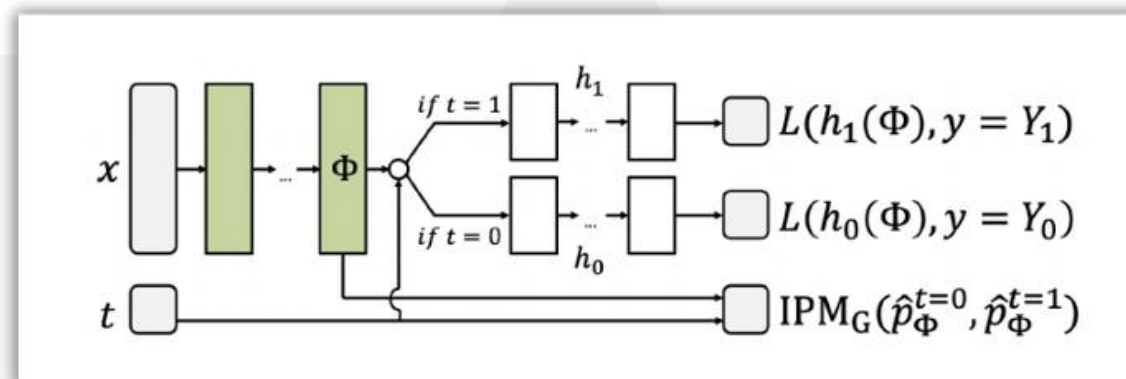
$\mathcal{L}_Y$  Same TARNet prediction loss

$$\mathcal{L}_T = - \sum_i [ T_i \log \hat{e}(X_i) + (1 - T_i) \log(1 - \hat{e}(X_i))]$$

**Propensity-supervised Treatment Loss**

$\mathcal{L}_{\text{targeted}}$  **Targeted Learning Loss**

It's a little parametric measurement to ensure that loss correction is doubly-robust: each update must be coherent with a causal update.



# Doubly Robust Learner (Q&A)



## Pseudo-outcome

- If PS is wrong but outcome is correct → still **ok**
- If outcome wrong but PS correct → still **ok**

This is **double robustness** extended to CATE.

DR estimator follows this schema:

**Baseline outcome model +  
propensity-weighted residual correction**

$$\mathbb{E}\left[\frac{T}{\hat{e}(X)}(Y - m_1(X)) \mid X\right] = \frac{e(X)}{\hat{e}(X)}\mathbb{E}[Y - m_1(X) \mid X, T = 1]$$

Let's assume estimated PS is wrong:

- If its too big → under-correction
- If its too small → over-correction

## Influence-function-based Pseudo-outcome

$$\psi_i = \underbrace{\hat{m}_1(X_i) - \hat{m}_0(X_i)}_{\text{Estimates Delta}} + \frac{T_i}{\hat{e}(X_i)} \underbrace{(Y_i - \hat{m}_1(X_i))}_{\text{Error on Treated}} - \frac{1 - T_i}{1 - \hat{e}(X_i)} \underbrace{(Y_i - \hat{m}_0(X_i))}_{\text{Error on Control}}$$

- If  $m_t(X)$  correct, the residues are zero → IPW terms ignorable (on average)
- If  $e(X)$  is correct, IPW weights correct  $m_t(X)$  error

# The Geometry (Q&A)



## Hilbert Space

Hilbert Space (HS) extends Euclidean geometry to functions :

- **Dot product**, compute angles and orthogonality:  $\langle f, g \rangle = \sum_{i=1}^n u_i v_i$
- **Norm** (L2), “amplitude/energy”:  $\|f\| = \sqrt{\langle f, f \rangle}$
- **Completeness**: limits of sequences tends to values inside the space. Needed for Optimization (e.g. gradient descent)

Usually we use, *L squared*, where the integral of the square of the function must be finite:  $\int f(x)^2 dx < \infty$

Dot product, here is:  $\langle f, g \rangle = \int f(x)g(x)dx$

## RKHS

### Problem

- Two functions,  $f$  and  $g$ , may have distance equal to zero but have different values in a specific point in HS due to punctual evaluation not being a continuous functional.

### RKHS: Reproducing Kernel Hilbert Space

- “Special” space where we impose that an *evaluation functional* must be continuous and limited:

$$|f(x)| \leq C_x \|f\|_{\mathcal{H}} \quad \forall x \in \mathcal{X}$$

## Riesz Representation Theorem

In a Hilbert space, if a linear functional is continuous there exists only one vector  $g$  in the space, such that the functional can be expressed as a dot product with  $g$ .

**Reproducing Property** is the direct consequence:

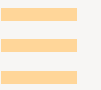
$$f(x) = \langle f, K_x \rangle_{\mathcal{H}}$$

With  $K$  point defined as **Feature Map**, uniquely mapping each raw point  $x$  in the Hilbert space.

We can now define the Kernel Function  $k(x, y)$ :

$$k(x, y) := \langle K_x, K_y \rangle_{\mathcal{H}} = K_x(y)$$

# Function Classes: $L^2$ vs RKHS (Q&A)



## Class of Functions

Why we need a function class  $\mathcal{F}$ :

$$IPM(p, q) = \sup_{f \in \mathcal{F}} |E_p[f(X)] - E_q[f(X)]|$$

- To avoid degenerate solutions, we must **restrict  $\mathcal{F}$** ;
- This class choice defines the **notion of distance**.

## $L^2$ space

$$\|f\|_{L^2}^2 = \int f(x)^2 dx < \infty$$

- Controls **global magnitude** of functions;
- Based on **integrals** (average behavior).
- Does **not control pointwise** values;
- **Unstable** for comparing individuals.

## RKHS

$$f(x) = \langle f, k(x, \cdot) \rangle$$

- HS with **kernel-induced geometry**;
- **Pointwise evaluation** is continuous;
- **Norm** controls function **everywhere**;
- Enables **kernel methods**;

## Pipeline

**Step 1 - Data:**  $x \in \mathbb{R}^d \rightarrow$  patient features

**Step 2 - Feature map:**  $\Phi(x) = k(x, \cdot) \rightarrow$  each patient becomes a similarity function

**Step 3 - Distribution embedding:**  $\mu_p = \mathbb{E}[\Phi(X)] \rightarrow$  distributions become mean functions

**Step 4 - Distance:** **MMD**  $\rightarrow$  compare treated vs control

**Geometry (kernel) + Averaging (expectation)  $\rightarrow$  Distribution Comparison**

# SUTVA Violations (Q&A)



## Consistency Example

- **Dataset:** Autistic Children in a RCT Study
- **Treatment:** Robot-assisted social skills intervention
- **Control group:** Physician-assisted Therapy
- **Outcome:** Improvements in social skills
  
- **Problem:** In control group, different children were followed by different doctors whose approach and outcome differs from each other
  
- **Consequence:** No consistency in control group

## No Interference Example

- **Dataset:** Adults in a community
- **Treatment:** Vaccine for a viral disease
- **Control:** No vaccine
- **Outcome:** Health improvement/Disease Incidence
  
- **Problem:** Control group is still “protected” from the disease due to Herd Immunity.
  
- **Consequence:** Assignment to subjects on Treatment Group influence outcome of Control Group → No interference violated.

**Often SUTVA violations derive from erroneous test definitions**

**Thanks!**  
**(Again)**